## Amendments to and Listing of the Claims:

The listing of the claims will replace all prior versions, and listings, of the claims in the application. Please amend claims 1-19 as follows:

1. (Currently amended) A fiducial marker holder apparatus [[<del>(20)</del>]] for image-guided surgery comprising:

an open-ended frame [[(30)]] having first and second arms (32, 33), the open-ended frame [[(30)]] being configured to be removably attached to a maxillary holding device [[(50)]] and the first arm [[(32)]] having at least one marker attachment point (48a, 48h) that receives fiducial markers [[(48)]]; and

a marker attachment device [[(40)]] disposed at a distal end of the second arm [[(33)]] of the open-ended frame [[(30)]], the marker attachment device [[(40)]] having a plurality of marker attachment points (48a 48h) that receive fiducial markers [[(48)]], at least two of the marker attachment points (48a 48h) of the marker attachment device [[(40)]] being configured to receive fiducial markers [[(48)]] in different orientations with respect to the marker attachment device [[(40)]] and each other (48a 48h).

- 2. (Currently amended) The fiducial marker holder apparatus [[(20)]] according to claim 1, wherein the marker attachment device [(40)] is movably attached to the second arm [(33)] of the open-ended frame [(30)].
- 3. (Currently amended) The fiducial marker holder apparatus [[(20)]] according to claim 2, wherein the marker attachment device [[(40)]] is configured to be fixedly oriented in more than one position.
- 4. (Currently amended) The fiducial marker holder apparatus [[(20)]] according to claim 1, further comprising an additional marker attachment device [[(40)]] disposed at a distal end of the first arm [[(32)]] of the open-ended frame [[(30)]], the additional

marker attachment device [[(40)]] having a plurality of marker attachment points (48a-48h) that receive fiducial markers [[(48)]].

- 5. (Currently amended) The fiducial marker holder apparatus [[(20)]] according to claim 1, wherein the marker attachment points (48a 48h) are each configured as one of a threaded socket, a threaded post, a through-hole, a post, a socket and a detent.
- 6. (Currently amended) A fiducial marker holder apparatus (120, 220) for image-guided surgery comprising:

a maxillary holding device [[(50)]] configured to be temporarily secured to only a maxillary-region of a patient;

an open-ended frame (130, 230) having first and second arms (132, 232, 133, 233), the open-ended frame (130, 230) being configured to be removably attached to the maxillary holding device [[(50)]], the first arm (132, 232) having at least one marker attachment point (148a-148n, 248a-248l) that receives fiducial markers [[(48)]] and the second arm (133, 233) having a plurality of marker attachment points (148a-148n, 248a-248l) that receive fiducial markers [[(48)]], at least two of the marker attachment points (148a-148n, 248a-248l) of the second arm (133, 233) being configured to receive fiducial markers [[(48)]] in different orientations with respect to the open-ended frame (130, 230) and each other (148a-148n, 248a-248l).

- 7. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the open-ended frame (130, 230) is rigid.
- 8. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the open-ended frame (130, 230) is formed of one of a carbon-fiber material, a non-metallic composite, and a polymeric material.

- 9. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the marker attachment points (148a 148n, 248a 2481) are each configured as one of a threaded socket, a threaded post, a through-hole, a post, a socket and a detent.
- 10. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the second arm (133, 233) has a first portion (133a, 233a) and a second portion (133b, 233b) extending at an angle  $[[(\alpha)]]$  from the first portion (133a, 233a).
- 11. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the first arm (132, 232) has a plurality of marker attachment points (148a, 248a, 248a, 2481) that receive fiducial markers [[(48)]] and the first arm (132, 232) has a first portion (132a, 232a) and a second portion (132b, 232b) extending at an angle [[(a)]] from the first portion (132a, 232a).
- 12. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the maxillary holding device [[(50)]] includes a locking dental acrylic resin splint that is custom molded for a particular patient.
- 13. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 6, wherein the maxillary holding device [[(50)]] is fastened directly to the patient by fasteners.
- 14. (Currently amended) A fiducial marker holder system (120, 220) for image-guided surgery comprising:
- a maxillary holding device [[(50)]] having a first clamping part [[(52)]], a second clamping part [[(54)]] and a fixing tool [[(56)]], the fixing tool [[(56)]] being configured to

temporarily secure the first and second clamping parts (52, 54) to only a maxillary-region of a patient;

an open-ended frame (130, 230) having first and second arms (132, 232, 133, 233), the open-ended frame (130, 230) being configured to be removably attached to the maxillary holding device [[(50)]], the first arm (133, 233) having at least one marker attachment point (148a 148n, 248a 248l) that receives fiducial markers [[(48)]] and the second arm (133, 233) having a plurality of marker attachment points (148a 148n, 248a 248l) that receive fiducial markers [[(48)]], at least two of the marker attachment points (148a 148n, 248a 248l) of the second arm (133, 233) being configured to receive fiducial markers [[(48)]] in different orientations with respect to the open-ended frame (130, 230) and each other (148a 148n, 248a 248l); and

a reference emitter [(90)] configured to be removably attached to the maxillary holding device [(50)] or the open-ended frame (130, 230).

- 15. (Currently amended) The fiducial marker holder system (120, 220) according to claim 14, wherein the open-ended frame (130, 230) is formed of a rigid material.
- 16. (Currently amended) The fiducial marker holder system (120, 220) according to claim 14, wherein the first arm (132, 232) has a plurality of marker attachment points (148a 148n, 248a 2481) that receive fiducial markers [[(48)]].
- 17. (Currently amended) The fiducial marker holder apparatus (120, 220) according to claim 14, wherein the marker attachment points (148a 148n, 248a 2481) are each configured as one of a threaded socket, a threaded post, a through-hole, a post, a socket and a detent.
- 18. (Currently amended) A method of performing image-guided surgery on a patient using a maxillary holding device [[(50)]], an open-ended frame (30, 130, 230), a plurality

of fiducial markers [[(48)]], a reference emitter [[(90)]], a surgical probe/instrument [[(320)]] and an image-guided surgical system [[(300)]] having a tracking sensor [[(325)]], the method comprising:

- (a) attaching the open-ended frame (30, 130, 230) with the plurality of fiducial markers [[(48)]] to a patient using the maxillary holding device [[(50)]];
- (b) acquiring a preoperative scan of the patient and the open-ended frame (30, 130, 230) with the plurality of fiducial markers [[(48)]];
  - (c) removing the maxillary holding device [[(50)]] from the patient;
  - (d) making a surgical plan, by the surgeon, from the preoperative scan;
- (e) calculating the position of any point in or on the patient relative to the frame (30, 130, 230);
  - (f) attaching the reference emitter [(90)] to the frame (30, 130, 230);
- (g) activating the tracking sensor [(325)] which then begins tracking the reference emitter [(90)] and the frame (30, 130, 230);
- (h) calibrating the frame (30, 130, 230) and the reference emitter [[(90)]], while the patient is being prepared for surgery, so that the position of the frame (30, 130, 230) relative to the reference emitter [[(90)]] is determined;
- (i) calculating the position of the frame (30, 130, 230) relative to the reference emitter (90)];
- (j) removing the frame (30, 130, 230) with the plurality of fiducial markers [[(48)]] from maxillary holding device [[(50)]];
- (k) attaching the maxillary holding device [(50)] with the reference emitter [(90)] to the patient;
- (l) calculating the position of any point in the intraoperative-imaged patient anatomy relative to the reference emitter [[(90)]];
  - (m) activating a surgical probe/instrument [[<del>(320)</del>]];

- (n) tracking the reference emitter [[(90)]] and the surgical probe/instrument [[(320)]] simultaneously;
- (o) calculating the position of the surgical probe/instrument [[(320)]] relative to the patient's anatomy; and
  - (p) using the image-guided surgical system [[(300)]] to guide surgery.
- 19. (Currently amended) A method of calibrating an image-guided surgical system [[(300)]] that is used to perform image-guided surgery on a patient using a maxillary holding device [[(50)]], an open-ended frame (30, 130, 230), a plurality of fiducial markers [[(48)]], a reference emitter [[(90)]], a surgical probe/instrument [[(320)]] and the image-guided surgical system [[(300)]] having memory and a tracking sensor [[(325)]], the method comprising:
- (a) attaching the open-ended frame (30, 130, 230) with the plurality of fiducial markers [[(48)]] to a patient using the maxillary holding device [[(50)]];
- (b) acquiring a preoperative scan of the patient and the open-ended frame (30, 13, 230) with the plurality of fiducial markers [[(48)]];
  - (c) removing the maxillary holding device [[(50)]] from the patient;
- (d) attaching the reference emitter [[(90)]] to either the open-ended frame (30, 130, 230) or the maxillary holding device [[(50)]];
- (e) activating the tracking sensor [(325)] which then begins tracking the reference emitter [(90)];
  - (f) activating the surgical probe/instrument [[(320)]];
- (g) tracking the reference emitter [(90)]] and the surgical probe/instrument [(320)]] simultaneously and continuously calculating the position of the surgical probe/instrument [(320)] relative to the reference emitter [(90)]; and
- (h) calibrating the image-guided surgical system [[(300)]] with respect to the frame (30, 130, 230) and the reference emitter [[(90)]] by touching the surgical probe/instrument [[(320)]] to each fiducial marker [[(48)]], so that the position of the frame (30, 130, 230) relative

to the reference emitter [[(90)]] is determined and stored in the memory of the image-guided surgical system [[(300)]].